This take-home exam has 100 points and is due at the beginning of class on Wednesday, Feb. 18.

Please submit printed output if possible. Otherwise, write legibly. Both the Word document and the pdf are posted. Points will be awarded to the extent that we understand an answer or how a design works.

Problem	Points	Score
1.	20	
2.	20	
3.	20	
4.	20	
5.	20	
Total	100	

## **1. Hardware:** (short answer—no more than two sentences)

a. What is the purpose of a **current limiting resistor** in a circuit?

b. Why do we need to use **pull-up resistors**? What is an example where you would need to use one?

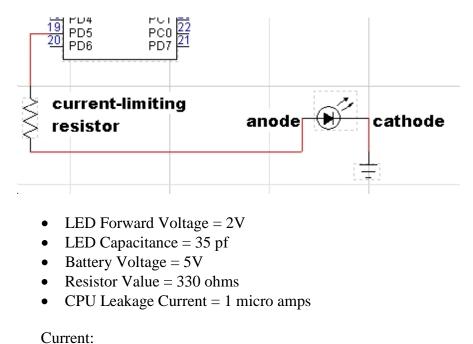
c. Why would you want to add bypass capacitors to your circuit?

d. The ATmega16 is an example of "Princeton architecture" or "Harvard architecture?"

What is the main difference between these two architectures?

Name \_\_\_

e. Calculate the current through the LED given the following:



f. Describe the sequence of events when an interrupt occurs on the ATmega16. Indicate what elements of the interrupt sequence are managed by the hardware and what elements must be managed by the software.

2. Describe the function of each of these registers (where x can be any timer number). Give examples of how these registers would or could be used in Lab3 (Tri-Color LED controller)? For each register you should describe how the register is used to generate or service any of the following interrupts: Overflow, Input Capture, and Output Compare.

a. OCRx

b. ICRx

c. TCNTx

3. The LIS3L02DQ (<u>datasheet</u>) is a three axis digital output linear accelerometer. Your job is to connect this part using the I2C (TWI) interface to an ATmega16 microcontroller. (The SPI interface is taken by another peripheral in this design).

a. List pins on the ATmega16 that connect to pins on the LIS3L02DQ. In addition, show any other pin connections that need to be made on the LIS3L02DQ to ensure proper operation of the I2C interface. The LIS3L02DQ is the only peripheral on this I2C bus. You do not need to show power and ground connections.

ATmega16 pins LIS3L02DQ pins Function

b. Write a driver to initialize the LIS3L02DQ, and to acquire data from it. **Hand in a print-out** of your driver, properly commented so that we can understand how it works.

4. In Labs 3 and 4 you built a one-dimensional electric field sensor that was able to sense the distance to your hand or other grounded objects. **Describe how** you would re-design this with a single receiving antenna and multiple transmitting antennas to capture movement in the X, Y, and Z axes. Use additional sheets if necessary.

Be certain that you answer the following:

a. What hardware changes are required?

b. What software changes are required?

c. Estimate the speed of operation of this new controller. How fast can you obtain readings in three axes, compared to the operation of your single-axis sensor in labs 3 and 4?

Name \_

5. A temperature monitor is being designed around a germanium diode. The diode's forward voltage drop is a strong function of temperature. Therefore, a direct voltage measurement across the diode must be made to determine the temperature. Design an ADC interface using the AVR that will accomplish this, subject to the requirements below:

-Only port A I/O pins may be used.

-The reference voltage will be Vdd for the chip (AREF).

-No additional parts may be used.

-AVR CPU clock 8MHz

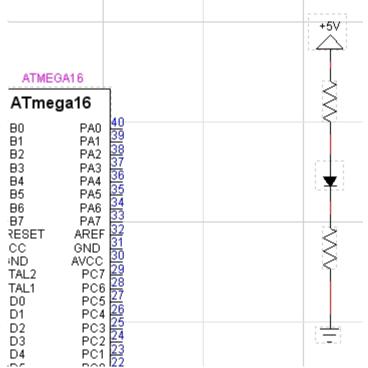
## -Convert as fast as possible

-LSB of result will be in bit 0 of ADCL.

-The ADC configuration must maximize the sensitivity to the diode's voltage variations.

-The forward voltage drop of the diode ranges from 0.28V to 0.38V over the temperature of interest.

## a. Finish the schematic below:



b. Show the values for the following registers. Bits that do not affect ADC operation may be left blank:

7	6	5	4	3	2	1	0

ADCSRA

7	6	5	4	3	2	1	0